



SAR Test Report

APPLICANT : Panasales Clearance Center Pty. Ltd.TA cellsafe Pty. Ltd
EQUIPMENT : smart Radi chip
BRAND NAME : Cellsafe
MODEL NAME : smart radi chip for iphone 12
TEST DATE : 2020/11/23

The test results in this report apply exclusively to the tested model / sample. Without written approval of Sporton International (ShenZhen) Inc., the test report shall not be reproduced except in full.

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Revision History

REPORT NO.	VERSION	DESCRIPTION	ISSUED DATE
NS0D1208	Rev. 01	Initial issue of report	Dec. 09, 2020

1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for **Panasales Clearance Center Pty. Ltd.TA cellsafe Pty. Ltd, smart Radi chip, smart radi chip for iphone 12**, are as follows.

Sample	Frequency Band	Highest SAR Summary			
		With Smart Radi Chip		Without Smart Radi Chip	
		1g SAR (W/kg)	10g SAR (W/kg)	1g SAR (W/kg)	10g SAR (W/kg)
iphone 12	WCDMA Band II	0.159	0.092	0.397	0.222
Date of Testing:		2020/11/23			

2. Administration Data

Testing Laboratory	
Test Site	Sporton International (Shenzhen) Inc.
Test Site Location	1/F, 2/F, Bldg 5, Shiling Industrial Zone, Xinwei Village, Xili, Nanshan, Shenzhen, 518055 People's Republic of China TEL: +86-755-86379589 FAX: +86-755-86379595

Applicant	
Company Name	Panasales Clearance Center Pty. Ltd.TA cellsafe Pty. Ltd
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3. Equipment Under Test (EUT) Information

3.1 General Information

Product Feature & Specification	
Equipment Name	smart Radi chip
Brand Name	Cellsafe
Model Name	smart radi chip for iphone 12
Wireless Technology and Frequency Range	WCDMA Band II: 1852.4 MHz ~ 1907.6 MHz

4. RF Exposure Limits

4.1 Uncontrolled Environment

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

4.2 Controlled Environment

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. The exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

Limits for Occupational/Controlled Exposure (W/kg)

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.4	8.0	20.0

Limits for General Population/Uncontrolled Exposure (W/kg)

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.08	1.6	4.0

Whole-Body SAR is averaged over the entire body, partial-body SAR is averaged over any 1gram of tissue defined as a tissue volume in the shape of a cube. SAR for hands, wrists, feet and ankles is averaged over any 10 grams of tissue defined as a tissue volume in the shape of a cube.

5. Specific Absorption Rate (SAR)

5.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

5.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

6. System Description and Setup

The DASY system used for performing compliance tests consists of the following items:




- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic Field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP or Win7 and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

6.1 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

<EX3DV4 Probe>

Construction	Symmetric design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	
Frequency	10 MHz – >6 GHz Linearity: ± 0.2 dB (30 MHz – 6 GHz)	
Directivity	± 0.3 dB in TSL (rotation around probe axis) ± 0.5 dB in TSL (rotation normal to probe axis)	
Dynamic Range	10 μ W/g – >100 mW/g Linearity: ± 0.2 dB (noise: typically <1 μ W/g)	
Dimensions	Overall length: 337 mm (tip: 20 mm) Tip diameter: 2.5 mm (body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	

6.2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.


The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



Photo of DAE


6.3 Phantom

<SAM Twin Phantom>

Shell Thickness	2 ± 0.2 mm; Center ear point: 6 ± 0.2 mm	
Filling Volume	Approx. 25 liters	
Dimensions	Length: 1000 mm; Width: 500 mm; Height: adjustable feet	
Measurement Areas	Left Hand, Right Hand, Flat Phantom	

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

<ELI Phantom>

Shell Thickness	2 ± 0.2 mm (sagging: <1%)	
Filling Volume	Approx. 30 liters	
Dimensions	Major ellipse axis: 600 mm Minor axis: 400 mm	

The ELI phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.

6.4 Device Holder

<Mounting Device for Hand-Held Transmitter>

In combination with the Twin SAM V5.0/V5.0c or ELI phantoms, the Mounting Device for Hand-Held Transmitters enables rotation of the mounted transmitter device to specified spherical coordinates. At the heads, the rotation axis is at the ear opening. Transmitter devices can be easily and accurately positioned according to IEC 62209-1, IEEE 1528, FCC, or other specifications. The device holder can be locked for positioning at different phantom sections (left head, right head, flat). And upgrade kit to Mounting Device to enable easy mounting of wider devices like big smart-phones, e-books, small tablets, etc. It holds devices with width up to 140 mm.



Mounting Device for Hand-Held Transmitters



Mounting Device Adaptor for Wide-Phones

<Mounting Device for Laptops and other Body-Worn Transmitters>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the mounting device in place of the phone positioned. The extension is fully compatible with the SAM Twin and ELI phantoms.



Mounting Device for Laptops

7. Measurement Procedures

The measurement procedures are as follows:

<SAR measurement>

- (a) Use base station simulator to configure EUT WWAN transmission in radiated connection, at maximum RF power, in the highest power channel.
- (b) Place the EUT in the positions as Appendix D demonstrates.
- (c) Set scan area, grid size and other setting on the DASY software.
- (d) Measure SAR results for the highest power channel on each testing position.
- (e) Find out the largest SAR result on these testing positions of each band
- (f) Measure SAR results for other channels in worst SAR testing position if the reported SAR of highest power channel is larger than 0.8 W/kg

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

7.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g

7.2 Area Scan

The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in DASY software can find the maximum found in the scanned area, within a range of the global maximum. The range (in dB) is specified in the standards for compliance testing. For example, a 2 dB range is required in IEEE standard 1528 and IEC 62209 standards, whereby 3 dB is a requirement when compliance is assessed in accordance with the ARIB standard (Japan), if only one zoom scan follows the area scan, then only the absolute maximum will be taken as reference. For cases where multiple maximums are detected, the number of zoom scans has to be increased accordingly.

Area scan parameters extracted from FCC KDB 865664 D01v01r04 SAR measurement 100 MHz to 6 GHz.

	≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 ± 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5$ mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
Maximum area scan spatial resolution: $\Delta x_{\text{Area}}, \Delta y_{\text{Area}}$	≤ 2 GHz: ≤ 15 mm $2 - 3$ GHz: ≤ 12 mm	$3 - 4$ GHz: ≤ 12 mm $4 - 6$ GHz: ≤ 10 mm
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be \leq the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

8. Test Equipment List

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	1900MHz System Validation Kit	D1900V2	5d182	Dec. 07, 2018	Nov. 24, 2021
SPEAG	Data Acquisition Electronics	DAE4	1210	Jul. 27, 2020	Jul. 26, 2021
SPEAG	Dosimetric E-Field Probe	EX3DV4	3826	May 20, 2020	May 19, 2021
SPEAG	SAM Twin Phantom	QD 000 P40 CD	TP-1671	NCR	NCR
SPEAG	Phone Positioner	N/A	N/A	NCR	NCR
Anritsu	Radio communication analyzer	MT8820C	6201300653	Jul. 21, 2020	Jul. 20, 2021
Agilent	Network Analyzer	E5071C	MY46523671	Oct. 15, 2020	Oct. 14, 2021
Speag	Dielectric Assessment KIT	DAK-3.5	1138	May 19, 2020	May 18, 2021
Agilent	Signal Generator	N5181A	MY50145381	Dec. 26, 2019	Dec. 25, 2020
Anritsu	Power Sensor	MA2411B	1306099	Jul. 21, 2020	Jul. 20, 2021
Anritsu	Power Meter	ML2495A	1349001	Jul. 21, 2020	Jul. 20, 2021
Anritsu	Power Sensor	MA2411B	1207253	Dec. 26, 2019	Dec. 25, 2020
Anritsu	Power Meter	ML2495A	1218010	Dec. 26, 2019	Dec. 25, 2020
TES	Hygrometer	1310	200505600	Jul. 30, 2020	Jul. 29, 2021
Anymetre	Thermo-Hygrometer	JR593	2015030904	Jul. 21, 2020	Jul. 20, 2021
Anymetre	Thermo-Hygrometer	JR593	2018100801	Apr. 19, 2020	Apr. 18, 2021
AR	Amplifier	5S1G4	0333096	Note 1	
ARRA	Power Divider	A3200-2	N/A	Note 1	
PASTERNAK	Dual Directional Coupler	PE2214-10	N/A	Note 1	
Agilent	Dual Directional Coupler	778D	50422	Note 1	
MCL	Attenuator 1	BW-S10W5	N/A	Note 1	
Weinschel	Attenuator 2	3M-20	N/A	Note 1	
Zhongjilianhe	Attenuator 3	MVE2214-03	N/A	Note 1	

Note:

1. Prior to system verification and validation, the path loss from the signal generator to the system check source and the power meter, which includes the amplifier, cable, attenuator and directional coupler, was measured by the network analyzer. The reading of the power meter was offset by the path loss difference between the path to the power meter and the path to the system check source to monitor the actual power level fed to the system check source.
2. Referring to KDB 865664 D01v01r04, the dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
3. The justification data of dipole can be found in appendix C. The return loss is < -20dB, within 20% of prior calibration, the impedance is within 5 ohm of prior calibration.

9. System Verification

9.1 Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 10.1.

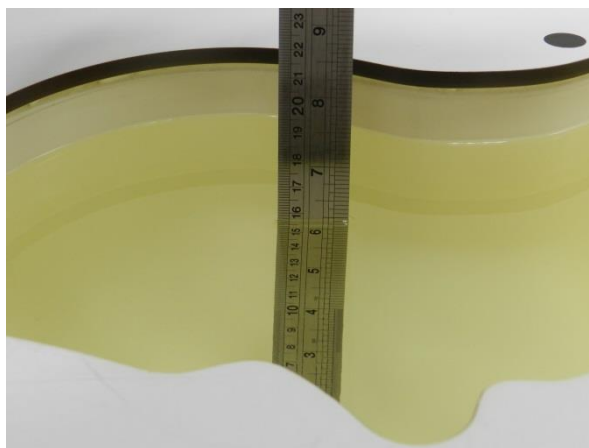


Fig 10.1 Photo of Liquid Height for Head SAR

9.2 Tissue Verification

The following tissue formulations are provided for reference only as some of the parameters have not been thoroughly verified. The composition of ingredients may be modified accordingly to achieve the desired target tissue parameters required for routine SAR evaluation.

Frequency (MHz)	Water (%)	Sugar (%)	Cellulose (%)	Salt (%)	Preventol (%)	DGBE (%)	Conductivity (σ)	Permittivity (ϵ_r)
For Head								
1900	55.2	0	0	0.3	0	44.5	1.40	40.0

<Tissue Dielectric Parameter Check Results>

Frequency (MHz)	Tissue Type	Liquid Temp. (°C)	Conductivity (σ)	Permittivity (ϵ_r)	Conductivity Target (σ)	Permittivity Target (ϵ_r)	Delta (σ) (%)	Delta (ϵ_r) (%)	Limit (%)	Date
1900	Head	22.5	1.440	40.038	1.40	40.00	2.86	0.09	±5	2020/11/23

9.3 System Performance Check Results

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10 %. Below table shows the target SAR and measured SAR after normalized to 1W input power. The table below indicates the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

1g SAR:

Date	Frequency (MHz)	Tissue Type	Input Power (mW)	Dipole S/N	Probe S/N	DAE S/N	Measured 1g SAR (W/kg)	Targeted 1g SAR (W/kg)	Normalized 1g SAR (W/kg)	Deviation (%)
2020/11/23	1900	Head	250	5d182	3826	1210	10.40	39.60	41.6	5.05

10g SAR:

Date	Frequency (MHz)	Tissue Type	Input Power (mW)	Dipole S/N	Probe S/N	DAE S/N	Measured 10g SAR (W/kg)	Targeted 10g SAR (W/kg)	Normalized 10g SAR (W/kg)	Deviation (%)
2020/11/23	1900	Head	250	5d182	3826	1210	5.29	20.70	21.16	2.22

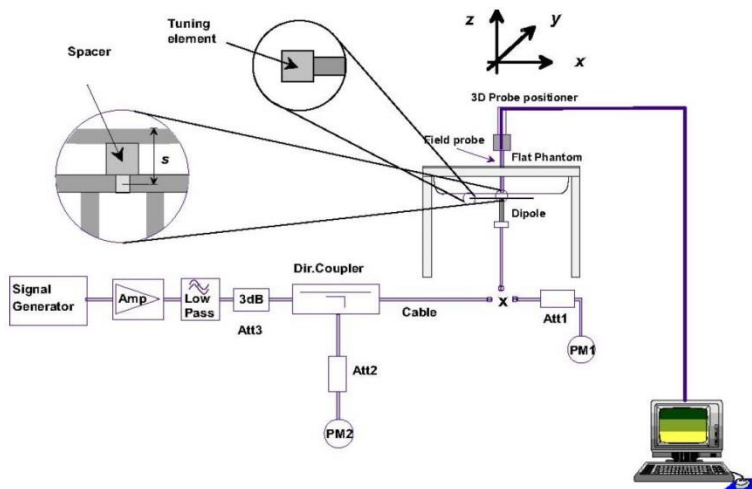


Fig 8.3.1 System Performance Check Setup



Fig 8.3.2 Setup Photo

10. RF Exposure Positions

10.1 Ear and handset reference point

Figure 9.1.1 shows the front, back, and side views of the SAM phantom. The center-of-mouth reference point is labeled "M," the left ear reference point (ERP) is marked "LE," and the right ERP is marked "RE." Each ERP is 15 mm along the B-M (back-mouth) line behind the entrance-to-ear-canal (EEC) point, as shown in Figure 9.1.2 The Reference Plane is defined as passing through the two ear reference points and point M. The line N-F (neck-front), also called the reference pivoting line, is normal to the Reference Plane and perpendicular to both a line passing through RE and LE and the B-M line (see Figure 9.1.3). Both N-F and B-M lines should be marked on the exterior of the phantom shell to facilitate handset positioning. Posterior to the N-F line the ear shape is a flat surface with 6 mm thickness at each ERP, and forward of the N-F line the ear is truncated, as illustrated in Figure 9.1.2. The ear truncation is introduced to preclude the ear lobe from interfering with handset tilt, which could lead to unstable positioning at the cheek.

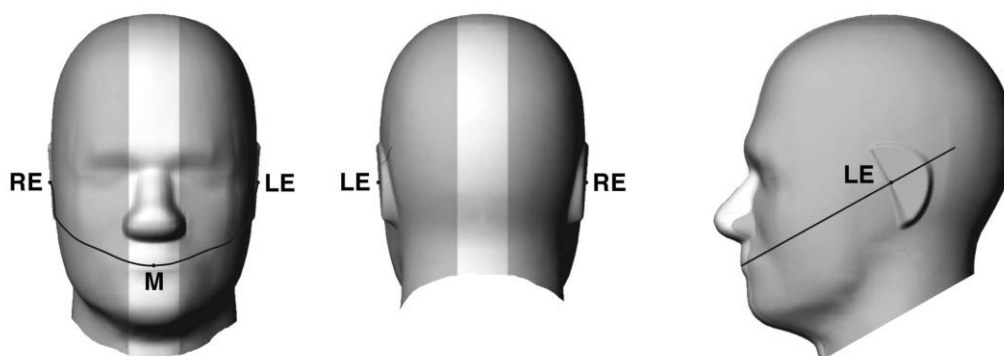


Fig 9.1.1 Front, back, and side views of SAM twin phantom

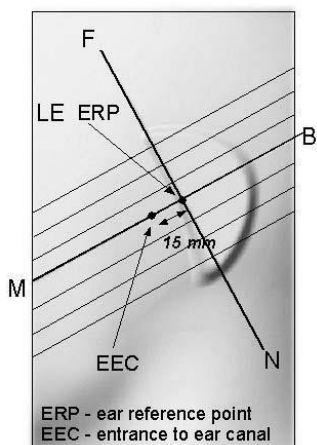


Fig 9.1.2 Close-up side view of phantom showing the ear region.

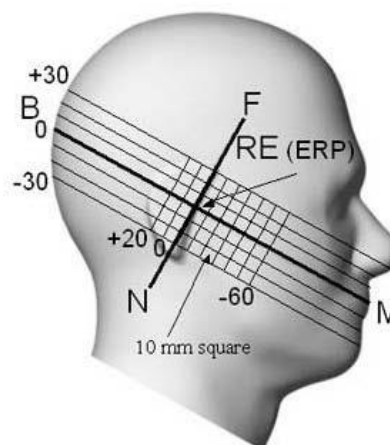


Fig 9.1.3 Side view of the phantom showing relevant markings and seven cross-sectional plane locations

10.2 Definition of the cheek position

1. Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece (flip cover), open the cover. If the handset can transmit with the cover closed, both configurations must be tested.
2. Define two imaginary lines on the handset—the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset—the midpoint of the width w_t of the handset at the level of the acoustic output (point A in Figure 9.2.1 and Figure 9.2.2), and the midpoint of the width w_b of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 9.2.1). The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output; however, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset (see Figure 9.2.2), especially for clamshell handsets, handsets with flip covers, and other irregularly-shaped handsets.
3. Position the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 9.2.3), such that the plane defined by the vertical centerline and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.
4. Translate the handset towards the phantom along the line passing through RE and LE until handset point A touches the pinna at the ERP.
5. While maintaining the handset in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to the plane containing B-M and N-F lines, i.e., the Reference Plane.
6. Rotate the handset around the vertical centerline until the handset (horizontal line) is parallel to the N-F line.
7. While maintaining the vertical centerline in the Reference Plane, keeping point A on the line passing through RE and LE, and maintaining the handset contact with the pinna, rotate the handset about the N-F line until any point on the handset is in contact with a phantom point below the pinna on the cheek. See Figure 9.2.3. The actual rotation angles should be documented in the test report.

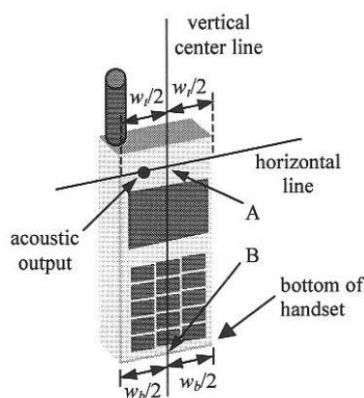


Fig 9.2.1 Handset vertical and horizontal reference lines—“fixed case”

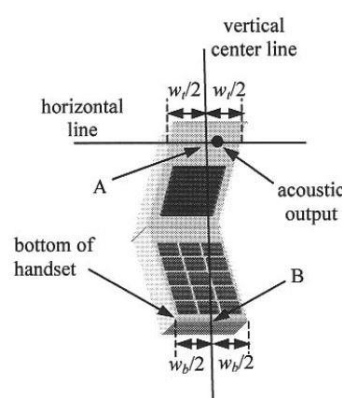


Fig 9.2.2 Handset vertical and horizontal reference lines—“clam-shell case”

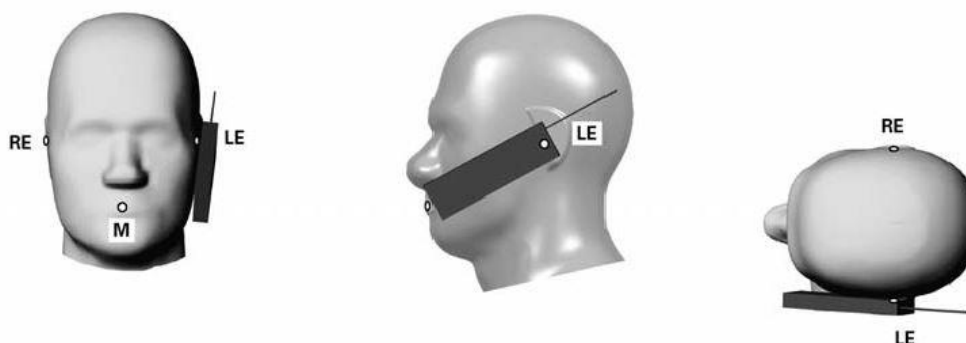


Fig 9.2.3 cheek or touch position. The reference points for the right ear (RE), left ear (LE), and mouth (M), which establish the Reference Plane for handset positioning, are indicated.

10.3 Definition of the tilt position

1. Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece (flip cover), open the cover. If the handset can transmit with the cover closed, both configurations must be tested.
2. While maintaining the orientation of the handset, move the handset away from the pinna along the line passing through RE and LE far enough to allow a rotation of the handset away from the cheek by 15°.
3. Rotate the handset around the horizontal line by 15°.
4. While maintaining the orientation of the handset, move the handset towards the phantom on the line passing through RE and LE until any part of the handset touches the ear. The tilt position is obtained when the contact point is on the pinna. See Figure 9.3.1. If contact occurs at any location other than the pinna, e.g., the antenna at the back of the phantom head, the angle of the handset should be reduced. In this case, the tilt position is obtained if any point on the handset is in contact with the pinna and a second point

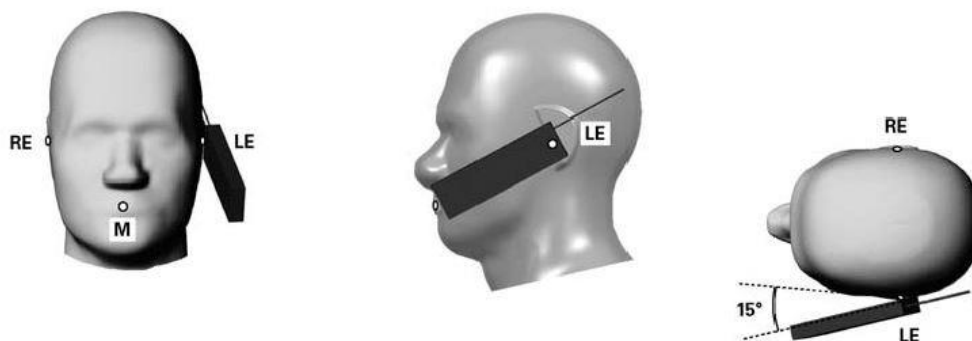


Fig 9.3.1 Tilt position. The reference points for the right ear (RE), left ear (LE), and mouth (M), which define the Reference Plane for handset positioning, are indicated.

11. SAR Test Results

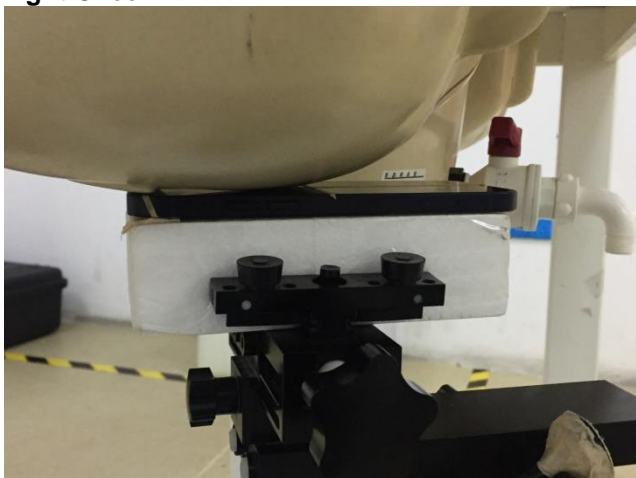
11.1 Head SAR

Plot No.	Band	Mode	Test Position	Ch.	Freq. (MHz)	Sample	Smart Radi chip	Measured 1g SAR (W/kg)	Measured 10g SAR (W/kg)
#01	WCDMA Band II	RMC 12.2Kbps	Right Cheek	9400	1880	iphone 12	Without	0.397	0.222
#02	WCDMA Band II	RMC 12.2Kbps	Right Cheek	9400	1880	iphone 12	With chip	0.159	0.092

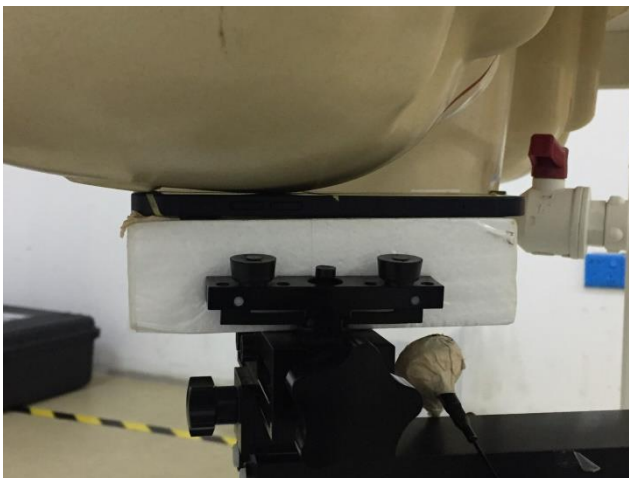
11.2 Test Sample and Test Setup Photographs



Right Cheek



iphone 12 with Smart Radi Chip



iphone 12 without Smart Radi Chip

12. Uncertainty Assessment

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in table below.

Uncertainty Distributions	Normal	Rectangular	Triangular	U-Shape
Multi-plying Factor ^(a)	$1/k^{(b)}$	$1/\sqrt{3}$	$1/\sqrt{6}$	$1/\sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) k is the coverage factor

Table 12.1. Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.

Error Description	Uncertainty Value (±%)	Probability	Divisor	(Ci) 1g	(Ci) 10g	Standard Uncertainty (1g) (±%)	Standard Uncertainty (10g) (±%)
Measurement System							
Probe Calibration	6.0	N	1	1	1	6.0	6.0
Axial Isotropy	4.7	R	1.732	0.7	0.7	1.9	1.9
Hemispherical Isotropy	9.6	R	1.732	0.7	0.7	3.9	3.9
Boundary Effects	1.0	R	1.732	1	1	0.6	0.6
Linearity	4.7	R	1.732	1	1	2.7	2.7
System Detection Limits	1.0	R	1.732	1	1	0.6	0.6
Modulation Response	3.2	R	1.732	1	1	1.8	1.8
Readout Electronics	0.3	N	1	1	1	0.3	0.3
Response Time	0.0	R	1.732	1	1	0.0	0.0
Integration Time	2.6	R	1.732	1	1	1.5	1.5
RF Ambient Noise	3.0	R	1.732	1	1	1.7	1.7
RF Ambient Reflections	3.0	R	1.732	1	1	1.7	1.7
Probe Positioner	0.4	R	1.732	1	1	0.2	0.2
Probe Positioning	2.9	R	1.732	1	1	1.7	1.7
Max. SAR Eval.	2.0	R	1.732	1	1	1.2	1.2
Test Sample Related							
Device Positioning	3.0	N	1	1	1	3.0	3.0
Device Holder	3.6	N	1	1	1	3.6	3.6
Power Drift	5.0	R	1.732	1	1	2.9	2.9
Power Scaling	0.0	R	1.732	1	1	0.0	0.0
Phantom and Setup							
Phantom Uncertainty	6.1	R	1.732	1	1	3.5	3.5
SAR correction	0.0	R	1.732	1	0.84	0.0	0.0
Liquid Conductivity Repeatability	0.2	N	1	0.78	0.71	0.1	0.1
Liquid Conductivity (target)	5.0	R	1.732	0.78	0.71	2.3	2.0
Liquid Conductivity (mea.)	2.5	R	1.732	0.78	0.71	1.1	1.0
Temp. unc. - Conductivity	3.4	R	1.732	0.78	0.71	1.5	1.4
Liquid Permittivity Repeatability	0.15	N	1	0.23	0.26	0.0	0.0
Liquid Permittivity (target)	5.0	R	1.732	0.23	0.26	0.7	0.8
Liquid Permittivity (mea.)	2.5	R	1.732	0.23	0.26	0.3	0.4
Temp. unc. - Permittivity	0.83	R	1.732	0.23	0.26	0.1	0.1
Combined Std. Uncertainty						11.4%	11.4%
Coverage Factor for 95 %						K=2	K=2
Expanded STD Uncertainty						22.9%	22.7%

Table 12.2. Uncertainty Budget for frequency range 300 MHz to 3 GHz



Appendix A. Plots of System Performance Check

The plots are shown as follows.

System Check_Head_1900MHz**DUT: D1900V2-SN:5d182**

Communication System: UID 0, CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium: HSL_1900_201123 Medium parameters used: $f = 1900$ MHz; $\sigma = 1.44$ S/m; $\epsilon_r = 40.038$; $\rho = 1000$ kg/m³

Ambient Temperature : 23.4 °C; Liquid Temperature : 22.5 °C

DASY5 Configuration:

- Probe: EX3DV4 - SN3826; ConvF(7.67, 7.67, 7.67); Calibrated: 2020.05.20;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1210; Calibrated: 2020.07.27
- Phantom: SAM2; Type: QD000P40CD; Serial: TP:1671
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7331)

Pin=250mW/Area Scan (61x61x1): Interpolated grid: dx=1.500 mm, dy=1.500 mm

Maximum value of SAR (interpolated) = 15.0 W/kg

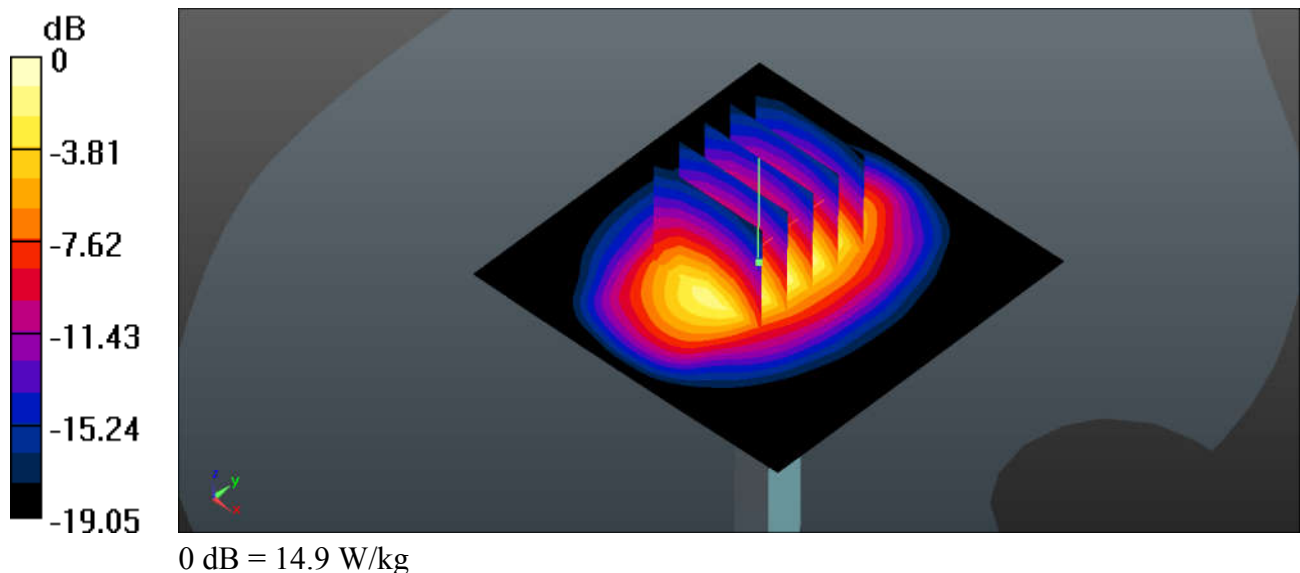
Pin=250mW/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 101.4 V/m; Power Drift = 0.18 dB

Peak SAR (extrapolated) = 19.5 W/kg

SAR(1 g) = 10.4 W/kg; SAR(10 g) = 5.29 W/kg

Maximum value of SAR (measured) = 14.9 W/kg





Appendix B. Plots of SAR Measurement

The plots are shown as follows.

#01_WCDMA II_RMC 12.2Kbps_Right Cheek_Ch9400_Without chip

Communication System: UID 0, UMTS (0); Frequency: 1880 MHz; Duty Cycle: 1:1

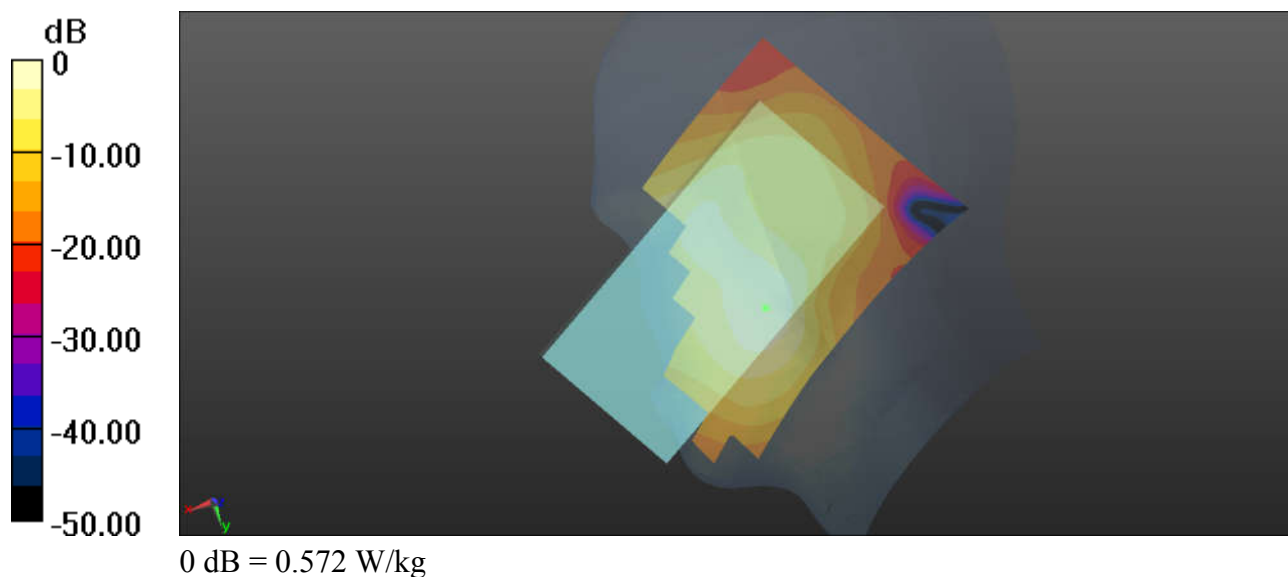
Medium: HSL_1900_201123 Medium parameters used: $f = 1880$ MHz; $\sigma = 1.42$ S/m; $\epsilon_r = 40.129$; $\rho = 1000$ kg/m³

Ambient Temperature : 23.4 °C; Liquid Temperature : 22.5 °C

DASY5 Configuration:

- Probe: EX3DV4 - SN3826; ConvF(7.67, 7.67, 7.67); Calibrated: 2020.05.20;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1210; Calibrated: 2020.07.27
- Phantom: SAM2; Type: QD000P40CD; Serial: TP:1671
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7331)

Ch9400/Area Scan (81x131x1): Interpolated grid: $dx=1.500$ mm, $dy=1.500$ mm
Maximum value of SAR (interpolated) = 0.572 W/kg



#02_WCDMA II_RMC 12.2Kbps_Right Cheek_Ch9400_With chip

Communication System: UID 0, UMTS (0); Frequency: 1880 MHz; Duty Cycle: 1:1

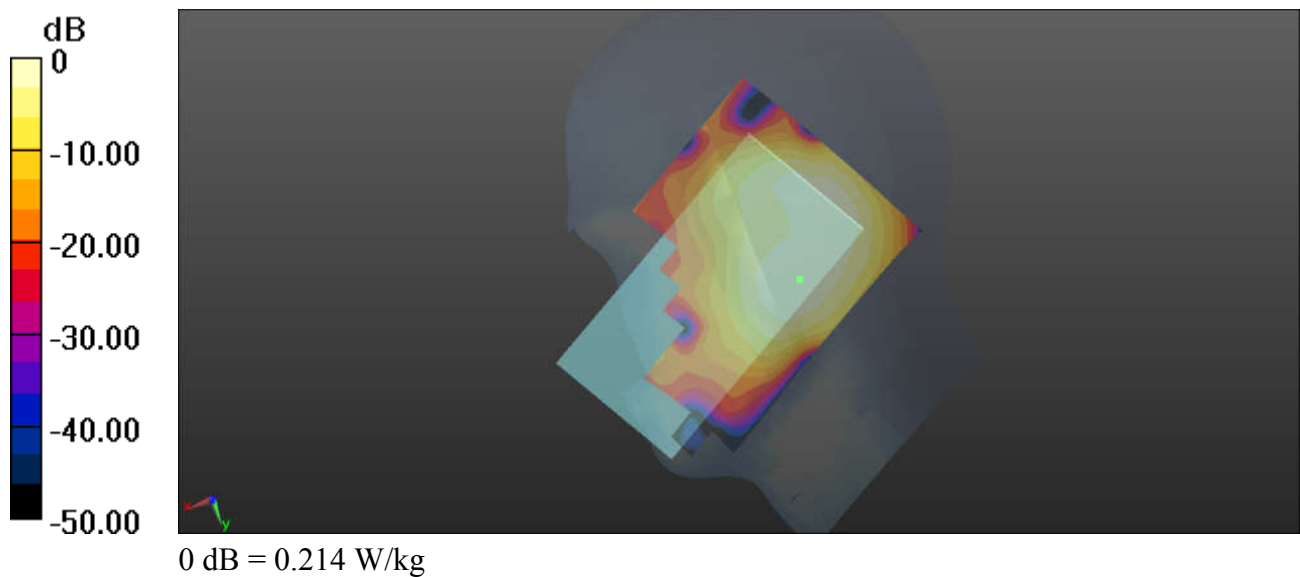
Medium: HSL_1900_201123 Medium parameters used: $f = 1880$ MHz; $\sigma = 1.42$ S/m; $\epsilon_r = 40.129$; $\rho = 1000$ kg/m³

Ambient Temperature : 23.4 °C; Liquid Temperature : 22.5 °C

DASY5 Configuration:

- Probe: EX3DV4 - SN3826; ConvF(7.67, 7.67, 7.67); Calibrated: 2020.05.20;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1210; Calibrated: 2020.07.27
- Phantom: SAM2; Type: QD000P40CD; Serial: TP:1671
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7331)

Ch9400/Area Scan (81x131x1): Interpolated grid: $dx=1.500$ mm, $dy=1.500$ mm
Maximum value of SAR (interpolated) = 0.214 W/kg





Appendix C. DASY Calibration Certificate

The DASY calibration certificates are shown as follows.



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Certificate No: **Z18-60536**

Client **Sporton**

CALIBRATION CERTIFICATE

Object **D1900V2 - SN: 5d182**

Calibration Procedure(s) **FF-Z11-003-01**
Calibration Procedures for dipole validation kits

Calibration date: **December 7, 2018**

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRVD	102196	07-Mar-18 (CTTL, No.J18X01510)	Mar-19
Power sensor NRV-Z5	100596	07-Mar-18 (CTTL, No.J18X01510)	Mar-19
Reference Probe EX3DV4	SN 7514	27-Aug-18(SPEAG,No.EX3-7514_Aug18)	Aug-19
DAE4	SN 1555	20-Aug-18(SPEAG,No.DAE4-1555_Aug18)	Aug-19
Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Signal Generator E4438C	MY49071430	23-Jan-18 (CTTL, No.J18X00560)	Jan-19
NetworkAnalyzer E5071C	MY46110673	24-Jan-18 (CTTL, No.J18X00561)	Jan-19

	Name	Function
Calibrated by:	Zhao Jing	SAR Test Engineer
Reviewed by:	Lin Hao	SAR Test Engineer
Approved by:	Qi Dianyuan	SAR Project Leader

Signature

Issued: December 10, 2018

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.



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lossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM _{x,y,z}
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Measurement procedure for assessment of specific absorption rate of human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices- Part 1: Device used next to the ear (Frequency range of 300MHz to 6GHz)", July 2016
- IEC 62209-2, "Procedure to measure the Specific Absorption Rate (SAR) For wireless communication devices used in close proximity to the human body (frequency range of 30MHz to 6GHz)", March 2010
- KDB865664, SAR Measurement Requirements for 100 MHz to 6 GHz

Additional Documentation:

- DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor $k=2$, which for a normal distribution Corresponds to a coverage probability of approximately 95%.



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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY52	52.10.2.1495
Extrapolation	Advanced Extrapolation	
Phantom	Triple Flat Phantom 5.1C	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	1900 MHz \pm 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	40.0	1.40 mho/m
Measured Head TSL parameters	(22.0 \pm 0.2) °C	39.6 \pm 6 %	1.44 mho/m \pm 6 %
Head TSL temperature change during test	<1.0 °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	10.1 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	39.6 mW / g \pm 18.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	5.25 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	20.7 mW / g \pm 18.7 % (k=2)

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	53.3	1.52 mho/m
Measured Body TSL parameters	(22.0 \pm 0.2) °C	51.8 \pm 6 %	1.56 mho/m \pm 6 %
Body TSL temperature change during test	<1.0 °C	----	----

SAR result with Body TSL

SAR averaged over 1 cm ³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	10.2 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	39.9 mW / g \pm 18.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	5.31 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	20.9 mW / g \pm 18.7 % (k=2)



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Appendix (Additional assessments outside the scope of CNAS L0570)

Antenna Parameters with Head TSL

Impedance, transformed to feed point	$52.1\Omega + 5.35j\Omega$
Return Loss	- 25.0dB

Antenna Parameters with Body TSL

Impedance, transformed to feed point	$48.9\Omega + 6.19j\Omega$
Return Loss	- 24.0dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.067 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard. No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

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Date: 12.06.2018

DASY5 Validation Report for Head TSL

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d182

Communication System: UID 0, CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 1900$ MHz; $\sigma = 1.441$ S/m; $\epsilon_r = 39.59$; $\rho = 1000$ kg/m³

Phantom section: Center Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7514; ConvF(7.73, 7.73, 7.73) @ 1900 MHz; Calibrated: 8/27/2018
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1555; Calibrated: 8/20/2018
- Phantom: MFP_V5.1C ; Type: QD 000 P51CA; Serial: 1062
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7450)

System Performance Check/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid:

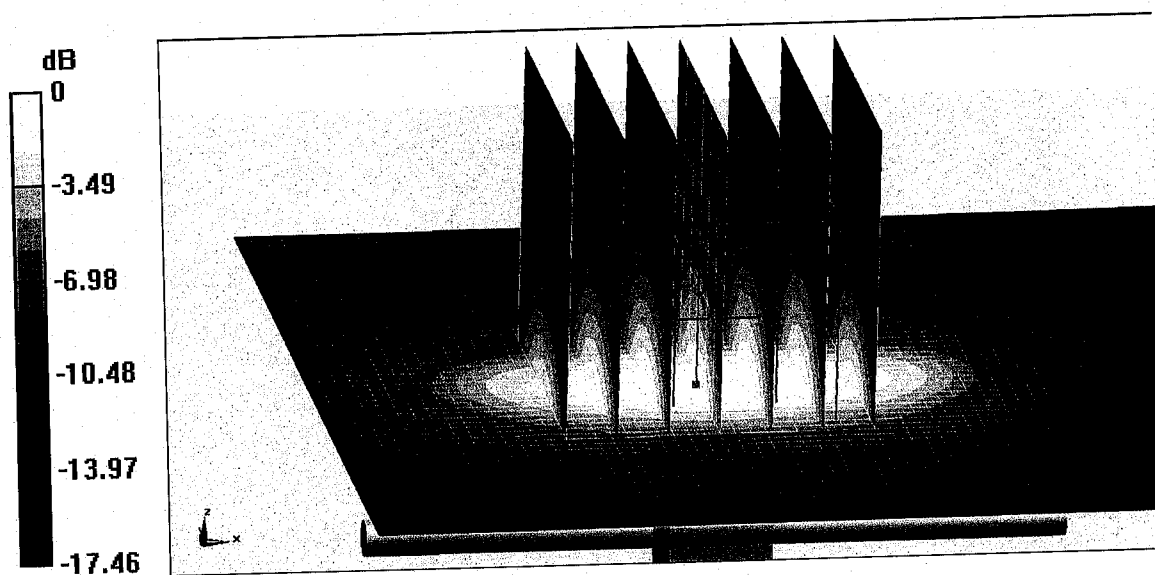
$dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 95.91 V/m; Power Drift = 0.00 dB

Peak SAR (extrapolated) = 19.3 W/kg

SAR(1 g) = 10.1 W/kg; SAR(10 g) = 5.25 W/kg

Maximum value of SAR (measured) = 15.8 W/kg



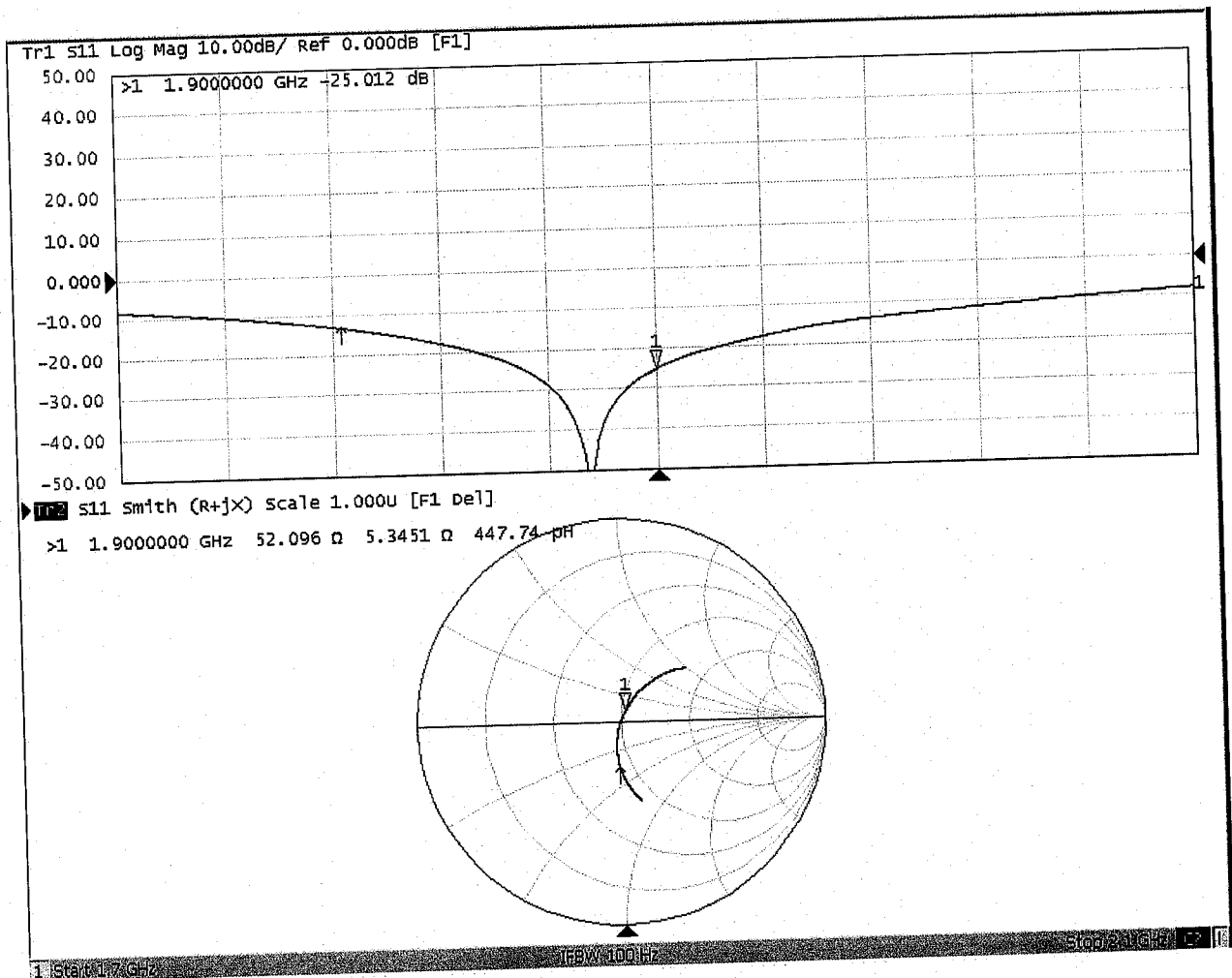
0 dB = 15.8 W/kg = 11.99 dBW/kg



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Impedance Measurement Plot for Head TSL





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DASY5 Validation Report for Body TSL

Date: 12.05.2018

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d182

Communication System: UID 0, CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 1900$ MHz; $\sigma = 1.564$ S/m; $\epsilon_r = 51.82$; $\rho = 1000$ kg/m³

Phantom section: Right Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7514; ConvF(7.53, 7.53, 7.53) @ 1900 MHz; Calibrated: 8/27/2018
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1555; Calibrated: 8/20/2018
- Phantom: MFP_V5.1C ; Type: QD 000 P51CA; Serial: 1062
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7450)

System Performance Check/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid:

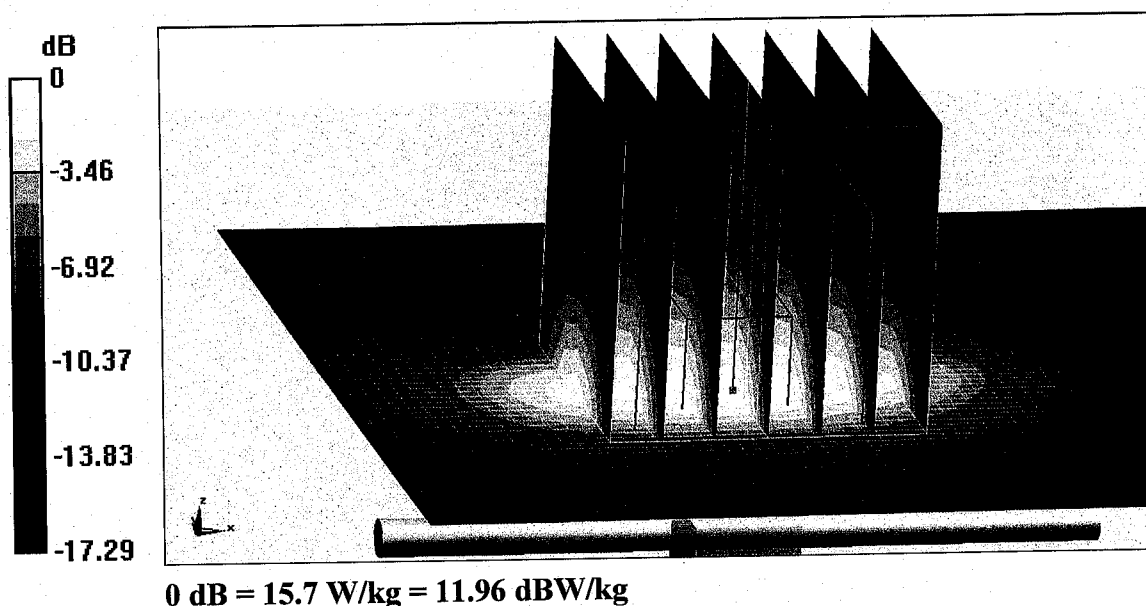
$dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 84.07 V/m; Power Drift = -0.04 dB

Peak SAR (extrapolated) = 18.9 W/kg

SAR(1 g) = 10.2 W/kg; SAR(10 g) = 5.31 W/kg

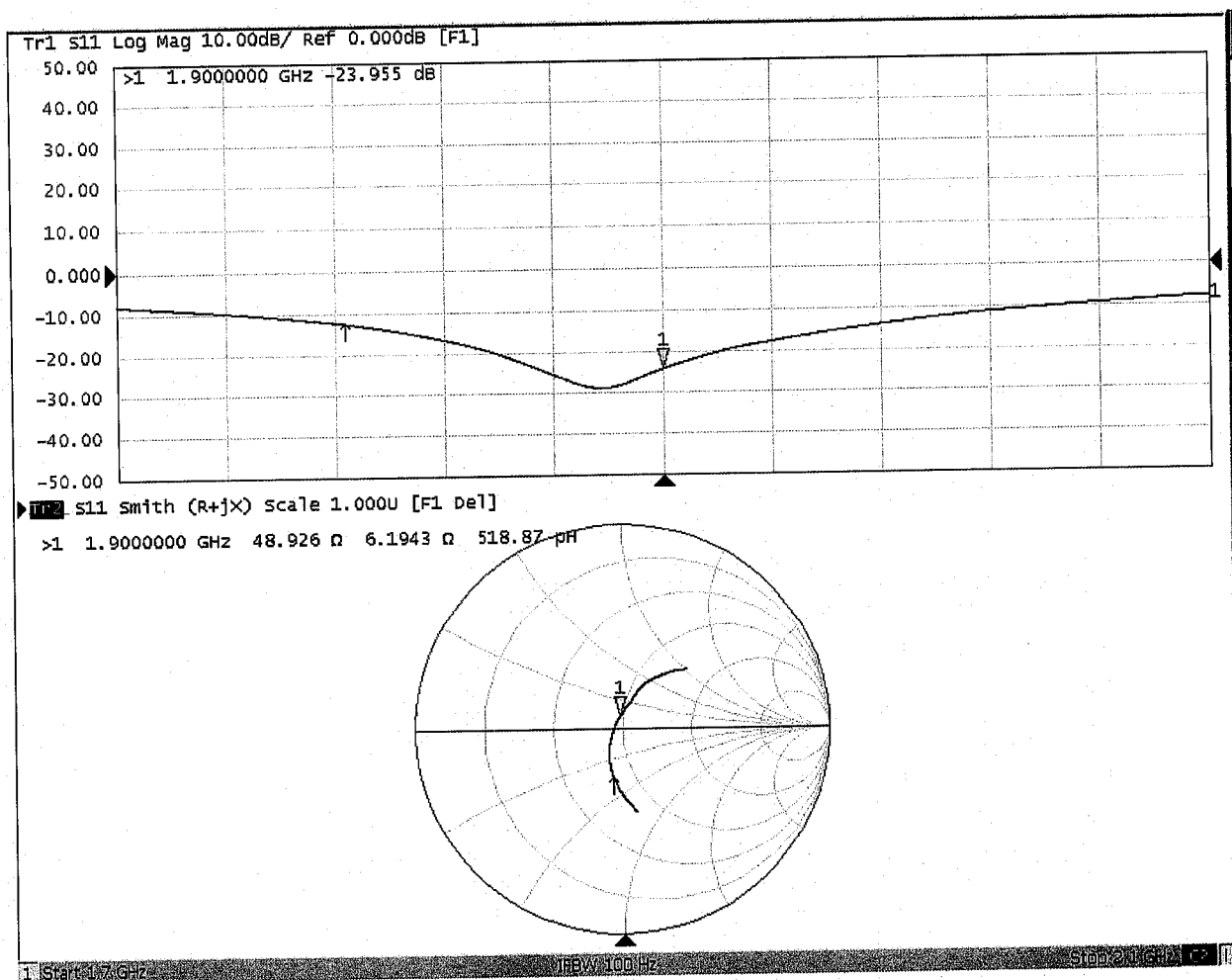
Maximum value of SAR (measured) = 15.7 W/kg





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Impedance Measurement Plot for Body TSL



D1900V2, Serial No. 5d182 Extended Dipole Calibrations

Referring to KDB 865664 D01 v01r02, if dipoles are verified in return loss ($< -20\text{dB}$, within 20% of prior calibration), and in impedance (within 5 ohm of prior calibration), the annual calibration is not necessary and the calibration interval can be extended.

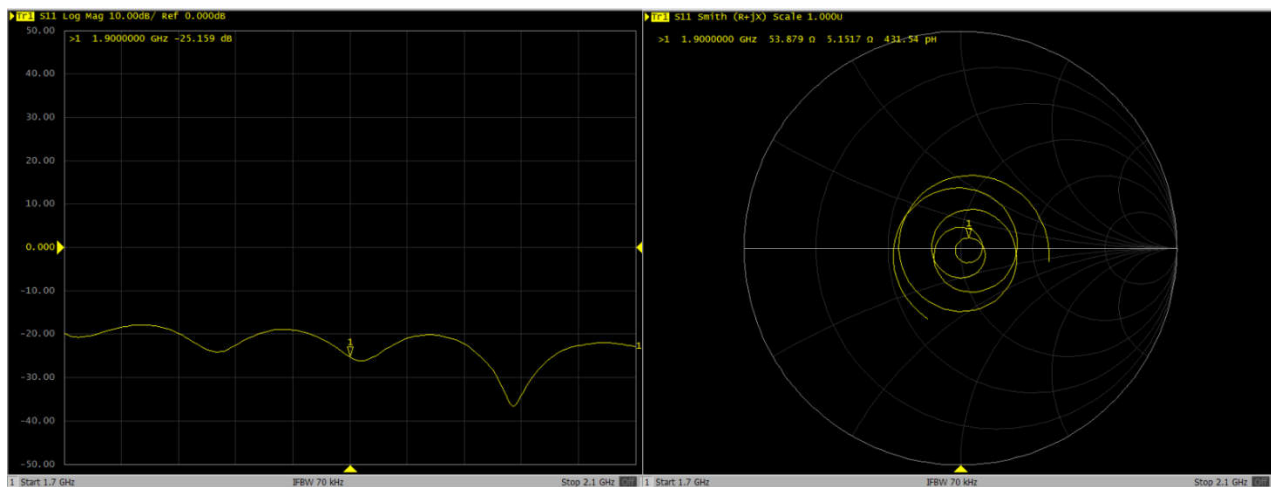
D1900V2 – serial no. 5d182												
	1900 Head						1900 Body					
Date of Measurement	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)	Return-Loss (dB)	Delta (%)	Real Impedance (ohm)	Delta (ohm)	Imaginary Impedance (ohm)	Delta (ohm)
2018.12.7	-25		52.1		5.35		-24		48.9		6.19	
2019.11.25	-25.2	-0.8	53.9	1.8	5.15	-0.2	-24.2	-0.8	48.7	-0.2	5.93	-0.26
2020.11.25	-25.8	3.2	52.6	0.5	4.56	-0.79	-24.2	-0.8	49.6	0.7	6.11	-0.08

<Justification of the extended calibration>

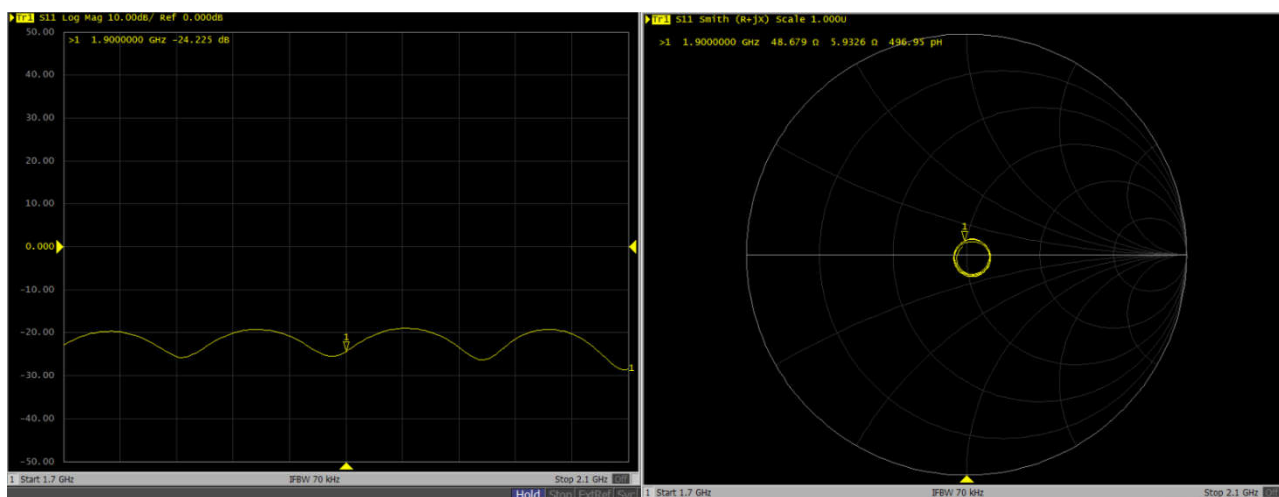
The return loss is $< -20\text{dB}$, within 20% of prior calibration; the impedance is within 5 ohm of prior calibration. Therefore the verification result should support extended calibration.

Dipole Verification Data> D1900V2, serial no. 5d182

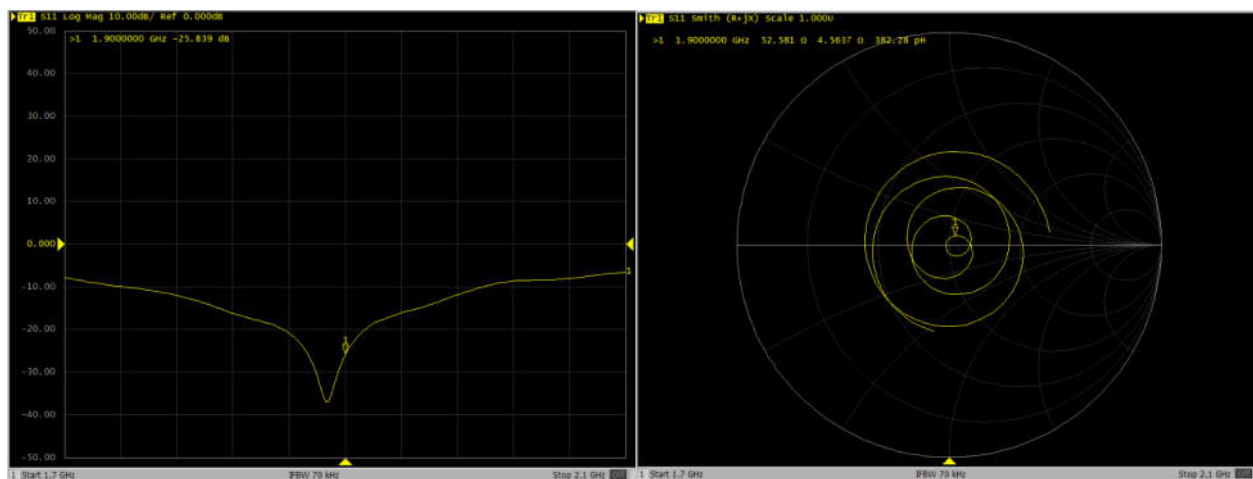
1900MHz – Head---2019.11.25



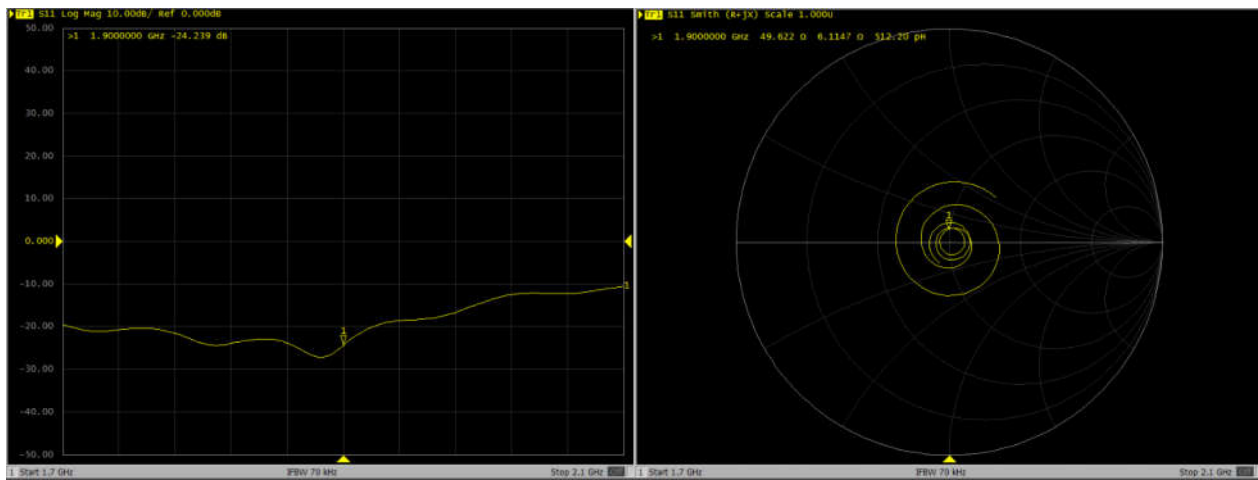
1900MHz – Body---2019.11.25



1900MHz – Head---2020.11.25



1900MHz – Body----2020.11.25



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IMPORTANT NOTICE

USAGE OF THE DAE4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE4 unit is fixed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

DASY Configuration Files: Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

Important Note:

Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

Important Note:

Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

Important Note:

To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.



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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Client **Sporton**

Certificate No: **DAE4-1210_Jul20**

CALIBRATION CERTIFICATE

Object **DAE4 - SD 000 D04 BM - SN: 1210**

Calibration procedure(s) **QA CAL-05.v30**
Calibration procedure for the data acquisition electronics (DAE)

Calibration date: **July 27, 2020**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility; environment temperature $(22 \pm 3)^{\circ}\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Kelthley Multimeter Type 2001	SN: 0810278	03-Sep-19 (No:25949)	Sep-20
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	09-Jan-20 (in house check)	In house check: Jan-21
Calibrator Box V2.1	SE UMS 008 AA 1002	09-Jan-20 (in house check)	In house check: Jan-21

Calibrated by:	Name Adrian Gehring	Function Laboratory Technician
Approved by:	Sven Kühn	Deputy Manager

Signature

Issued: July 27, 2020

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Accreditation No.: **SCS 0108**

Glossary

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- **DC Voltage Measurement:** Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- **Connector angle:** The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - **DC Voltage Measurement Linearity:** Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - **Common mode sensitivity:** Influence of a positive or negative common mode voltage on the differential measurement.
 - **Channel separation:** Influence of a voltage on the neighbor channels not subject to an input voltage.
 - **AD Converter Values with inputs shorted:** Values on the internal AD converter corresponding to zero input voltage
 - **Input Offset Measurement:** Output voltage and statistical results over a large number of zero voltage measurements.
 - **Input Offset Current:** Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - **Input resistance:** Typical value for information; DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - **Low Battery Alarm Voltage:** Typical value for information. Below this voltage, a battery alarm signal is generated.
 - **Power consumption:** Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V, full range = -100...+300 mV

Low Range: 1LSB = 61 nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.162 \pm 0.02% (k=2)	404.982 \pm 0.02% (k=2)	405.090 \pm 0.02% (k=2)
Low Range	3.99951 \pm 1.50% (k=2)	3.99092 \pm 1.50% (k=2)	3.95059 \pm 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	346.0 $^{\circ}$ \pm 1 $^{\circ}$
---	-------------------------------------

Appendix (Additional assessments outside the scope of SCS0108)

1. DC Voltage Linearity

High Range		Reading (μV)	Difference (μV)	Error (%)
Channel X	+ Input	199996.55	0.86	0.00
Channel X	+ Input	20003.46	1.82	0.01
Channel X	- Input	-19999.22	2.95	-0.01
Channel Y	+ Input	199995.01	-0.81	-0.00
Channel Y	+ Input	20000.50	-0.99	-0.00
Channel Y	- Input	-20001.74	0.48	-0.00
Channel Z	+ Input	199993.65	-2.05	-0.00
Channel Z	+ Input	20000.87	-0.52	-0.00
Channel Z	- Input	-20002.17	0.12	-0.00

Low Range		Reading (μV)	Difference (μV)	Error (%)
Channel X	+ Input	2001.48	0.71	0.04
Channel X	+ Input	202.17	0.99	0.49
Channel X	- Input	-198.74	-0.08	0.04
Channel Y	+ Input	2001.11	0.41	0.02
Channel Y	+ Input	200.90	-0.24	-0.12
Channel Y	- Input	-199.54	-0.82	0.42
Channel Z	+ Input	2000.50	-0.11	-0.01
Channel Z	+ Input	200.24	-0.82	-0.41
Channel Z	- Input	-199.89	-1.02	0.52

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-6.78	-8.90
	- 200	10.13	8.29
Channel Y	200	-8.84	-9.15
	- 200	8.75	8.46
Channel Z	200	12.20	12.07
	- 200	-14.74	-14.25

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	2.65	-4.04
Channel Y	200	8.36	-	2.84
Channel Z	200	9.58	7.02	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSE)	Low Range (LSB)
Channel X	15961	15923
Channel Y	15952	15701
Channel Z	15867	16022

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	-0.08	-1.17	1.37	0.42
Channel Y	-0.23	-1.47	0.68	0.40
Channel Z	0.14	-0.59	1.76	0.36

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

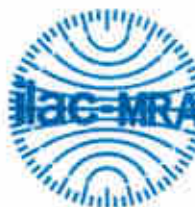
Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



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Client

Auden

Certificate No: **Z20-60166**

CALIBRATION CERTIFICATE

Object **EX3DV4 - SN : 3826**

Calibration Procedure(s) **FF-Z11-004-01**
Calibration Procedures for Dosimetric E-field Probes

Calibration date: **May 20, 2020**

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22 ± 3) $^{\circ}\text{C}$ and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	18-Jun-19(CTTL, No.J19X05125)	Jun-20
Power sensor NRP-Z91	101547	18-Jun-19(CTTL, No.J19X05125)	Jun-20
Power sensor NRP-Z91	101548	18-Jun-19(CTTL, No.J19X05125)	Jun-20
Reference 10dBAttenuator	18N50W-10dB	10-Feb-20(CTTL, No.J20X00525)	Feb-22
Reference 20dBAttenuator	18N50W-20dB	10-Feb-20(CTTL, No.J20X00526)	Feb-22
Reference Probe EX3DV4	SN 3617	30-Jan-20(SPEAG, No.EX3-3617_Jan20/2)	Jan-21
DAE4	SN 1556	4-Feb-20(SPEAG, No.DAE4-1556_Feb20)	Feb-21

Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
SignalGenerator MG3700A	6201052605	18-Jun-19(CTTL, No.J19X05127)	Jun-20
Network Analyzer E5071C	MY46110673	10-Feb-20(CTTL, No.J20X00515)	Feb-21

	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	
Reviewed by:	Lin Hao	SAR Test Engineer	
Approved by:	Qi Dianyuan	SAR Project Leader	

Issued: May 22, 2020

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Glossary:

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A,B,C,D	modulation dependent linearization parameters
Polarization Φ	Φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i $\theta=0$ is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Measurement procedure for the assessment of Specific Absorption Rate (SAR) from hand-held and body-mounted devices used next to the ear (frequency range of 300 MHz to 6 GHz)", July 2016
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}: Assessed for E-field polarization $\theta=0$ ($f \leq 900\text{MHz}$ in TEM-cell; $f > 1800\text{MHz}$: waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not effect the E^2 -field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP_{x,y,z}: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}; A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800\text{MHz}$) and inside waveguide using analytical field distributions based on power measurements for $f > 800\text{MHz}$. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from $\pm 50\text{MHz}$ to $\pm 100\text{MHz}$.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).



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E-mail: cttl@chinattl.com

[Http://www.chinattl.cn](http://www.chinattl.cn)**DASY/EASY – Parameters of Probe: EX3DV4 – SN:3826****Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc ($k=2$)
Norm($\mu V/(V/m)^2$) ^A	0.48	0.41	0.36	$\pm 10.0\%$
DCP(mV) ^B	100.2	99.8	103.2	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB/ μV	C	D dB	VR mV	Unc ^E ($k=2$)
0	CW	X	0.0	0.0	1.0	0.00	160.2	$\pm 2.7\%$
		Y	0.0	0.0	1.0		141.6	
		Z	0.0	0.0	1.0		130.8	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor $k=2$, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

^A The uncertainties of Norm X, Y, Z do not affect the E²-field uncertainty inside TSL (see Page 4).

^B Numerical linearization parameter; uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



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DASY/EASY – Parameters of Probe: EX3DV4 – SN:3826

Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	41.9	0.89	9.37	9.37	9.37	0.40	0.80	±12.1%
835	41.5	0.90	9.12	9.12	9.12	0.17	1.26	±12.1%
900	41.5	0.97	9.10	9.10	9.10	0.18	1.30	±12.1%
1750	40.1	1.37	7.98	7.98	7.98	0.19	1.14	±12.1%
1900	40.0	1.40	7.67	7.67	7.67	0.22	1.14	±12.1%
2000	40.0	1.40	7.77	7.77	7.77	0.24	1.10	±12.1%
2300	39.5	1.67	7.35	7.35	7.35	0.51	0.73	±12.1%
2450	39.2	1.80	7.12	7.12	7.12	0.53	0.72	±12.1%
2600	39.0	1.96	6.94	6.94	6.94	0.45	0.85	±12.1%
3500	37.9	2.91	6.62	6.62	6.62	0.39	0.98	±13.3%
5250	35.9	4.71	5.09	5.09	5.09	0.45	1.30	±13.3%
5600	35.5	5.07	4.66	4.66	4.66	0.45	1.40	±13.3%
5750	35.4	5.22	4.68	4.68	4.68	0.45	1.40	±13.3%

^C Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.



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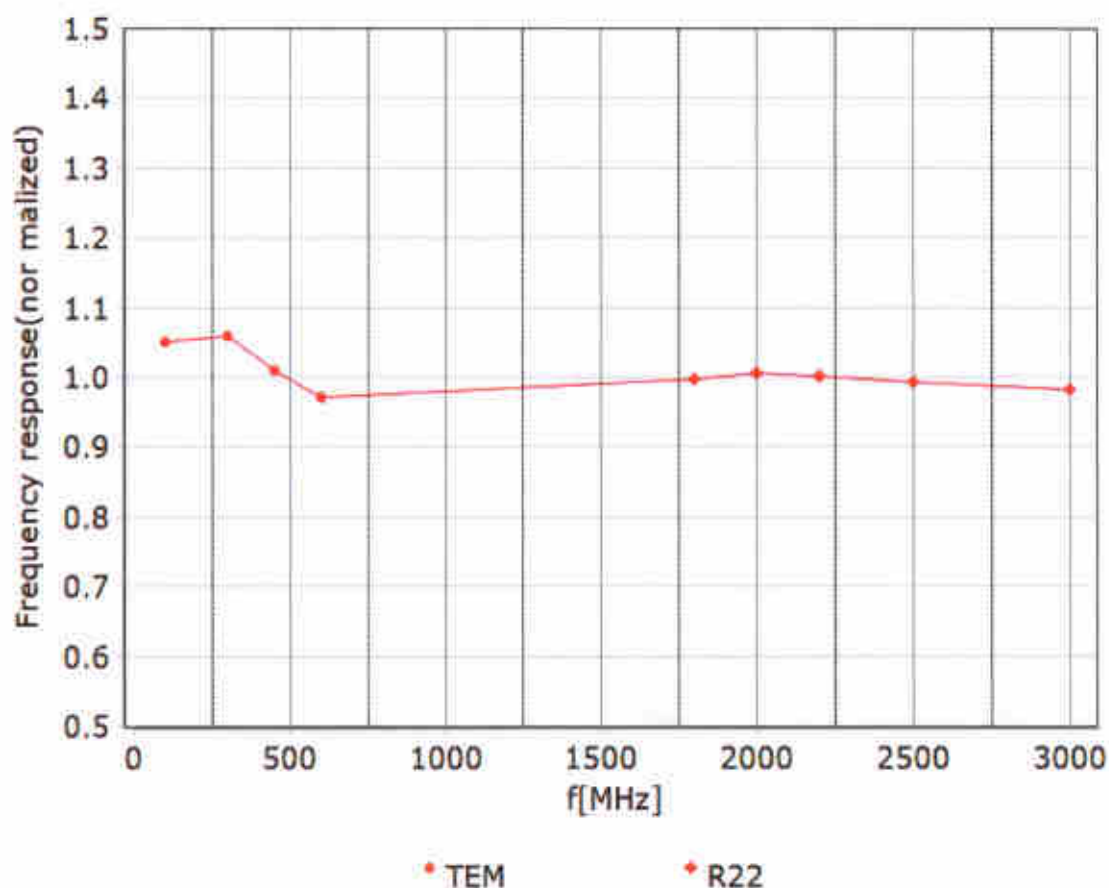
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Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: $\pm 7.4\%$ ($k=2$)

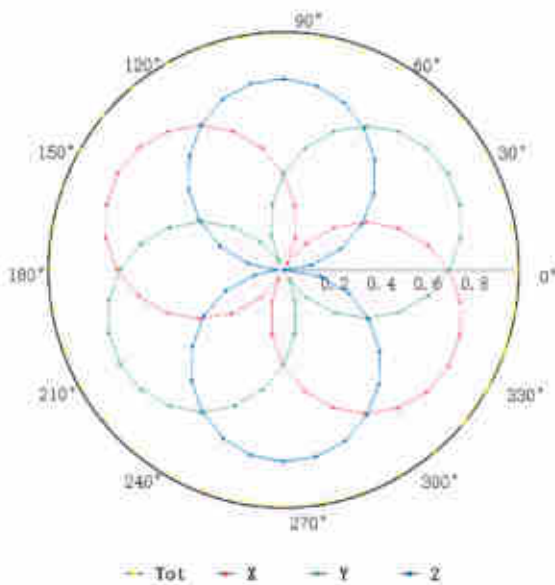


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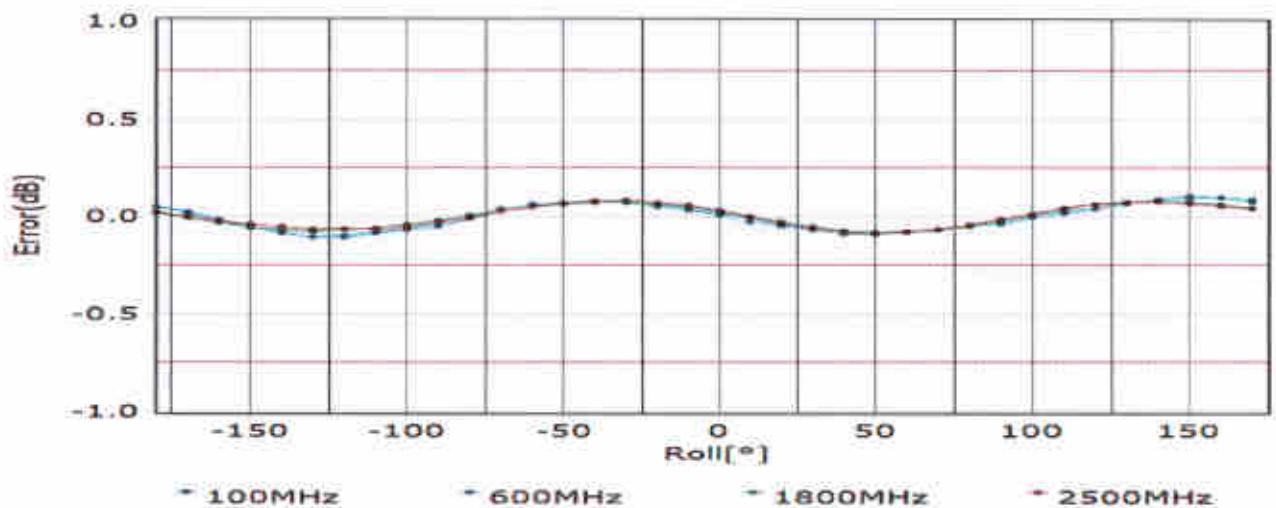
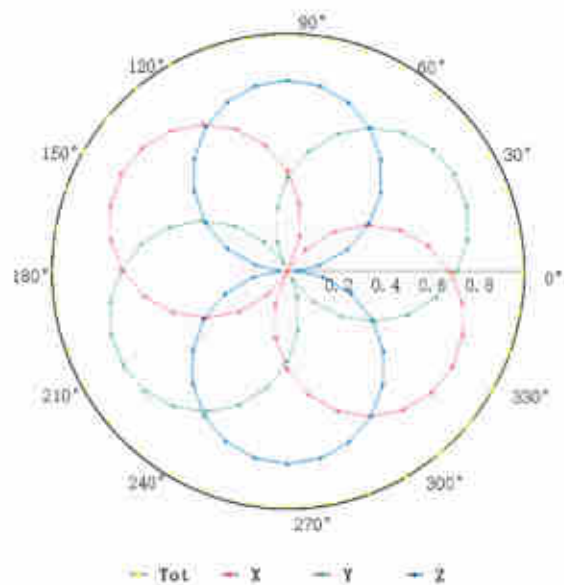
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Receiving Pattern (Φ), $\theta=0^\circ$

f=600 MHz, TEM



f=1800 MHz, R22



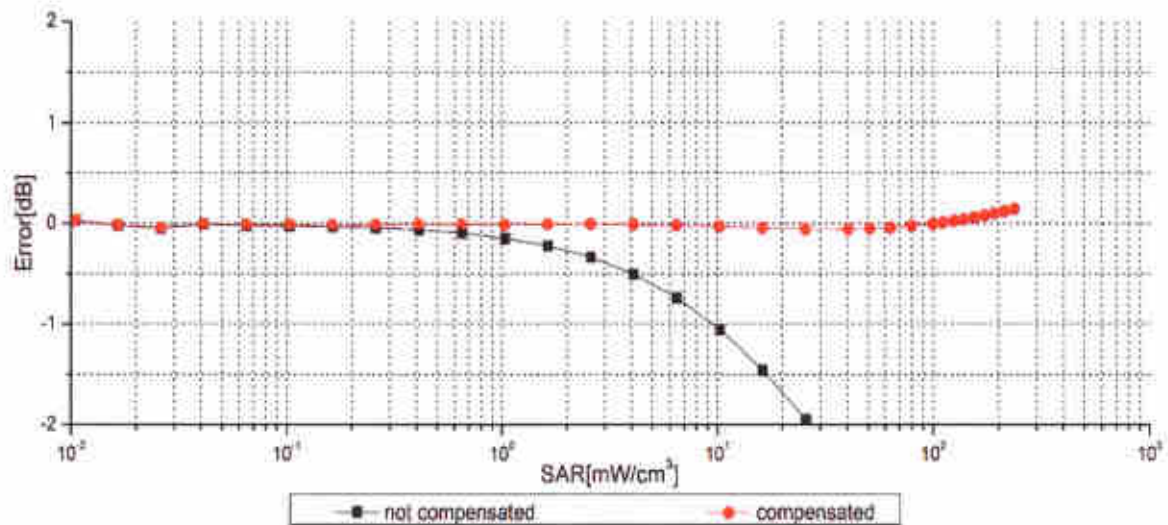
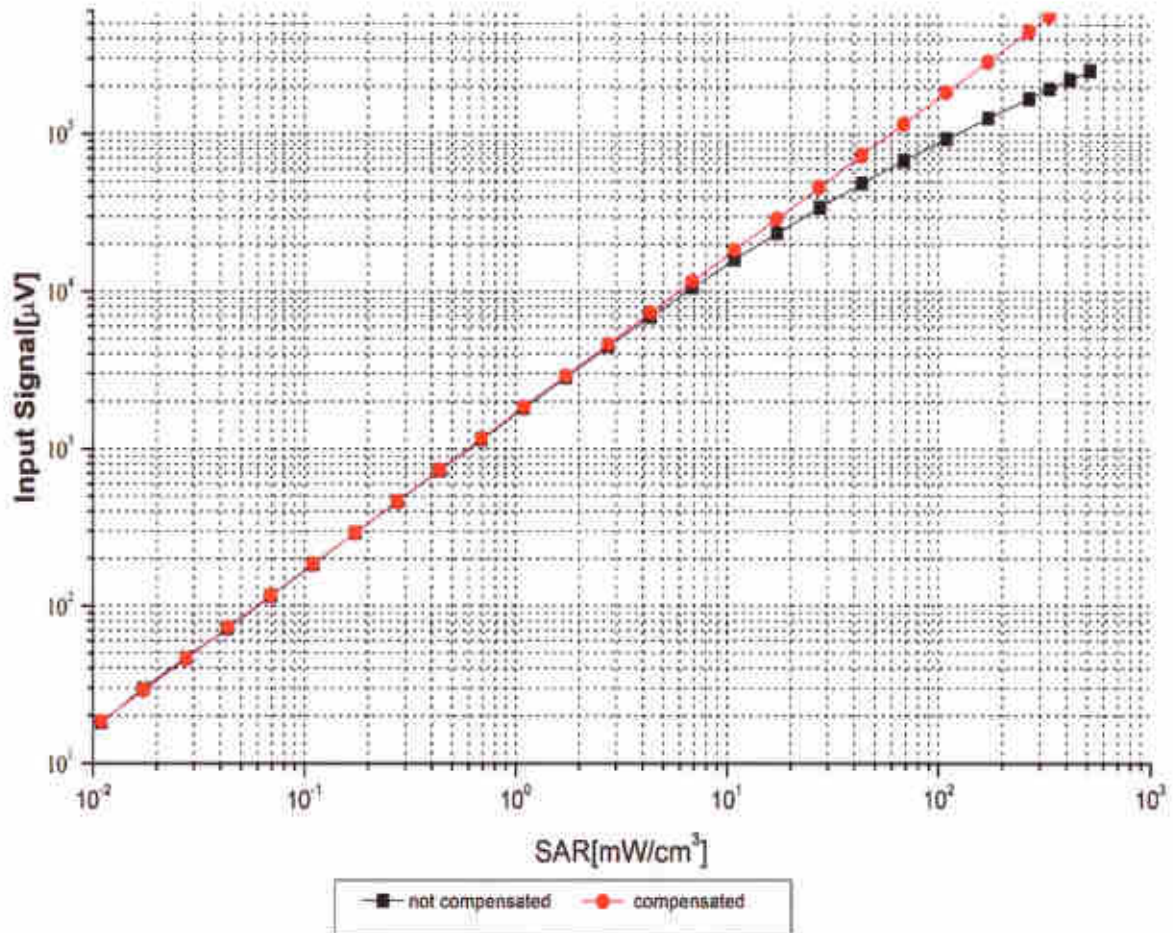
Uncertainty of Axial Isotropy Assessment: $\pm 1.2\%$ ($k=2$)



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Dynamic Range $f(\text{SAR}_{\text{head}})$ (TEM cell, $f = 900 \text{ MHz}$)



Uncertainty of Linearity Assessment: $\pm 0.9\%$ ($k=2$)



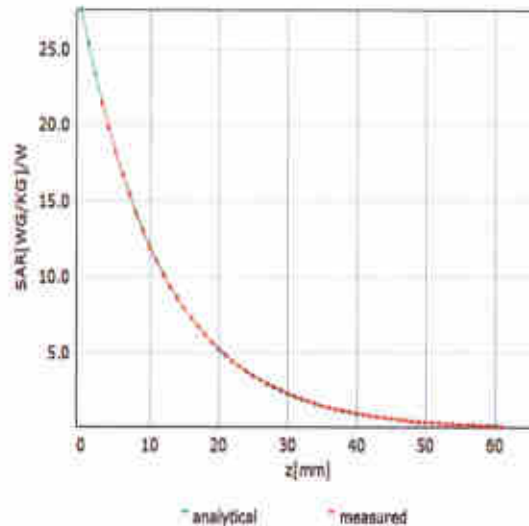
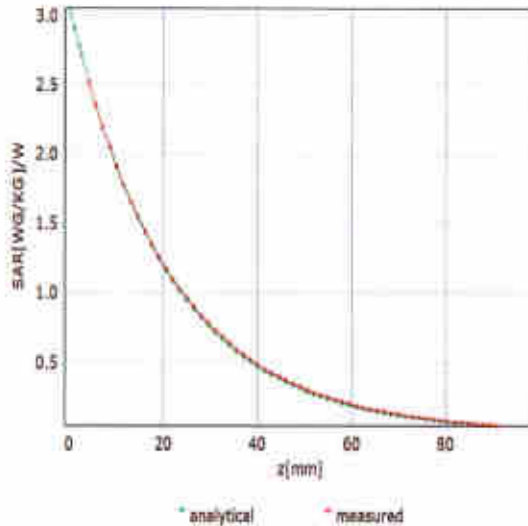
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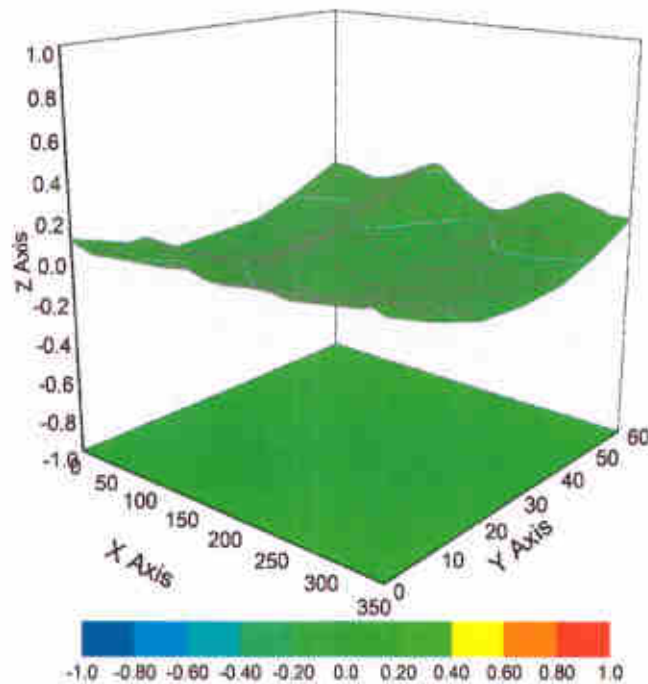
Conversion Factor Assessment

f=750 MHz,WGLS R9(H_convF)

f=1750 MHz,WGLS R22(H_convF)



Deviation from Isotropy in Liquid



Uncertainty of Spherical Isotropy Assessment: $\pm 3.2\%$ ($k=2$)



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DASY/EASY – Parameters of Probe: EX3DV4 – SN:3826

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	51.5
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	10mm
Tip Diameter	2.5mm
Probe Tip to Sensor X Calibration Point	1mm
Probe Tip to Sensor Y Calibration Point	1mm
Probe Tip to Sensor Z Calibration Point	1mm
Recommended Measurement Distance from Surface	1.4mm